### University of Eswatini



## MAIN EXAMINATION, 2020/2021

### M.Sc. in Mathematics

Title of Paper

: Optimization

Course Number

: MAT603

Time Allowed

: Three (3) Hours

#### Instructions

- 1. This paper consists of SEVEN (7) questions.
- 2. Answer ANY FIVE (5) questions.
- 3. Show all your working.
- 4. Start each new major question (Q1, Q2, ..., Q7) on a new page and clearly indicate the question number at the top of the page.
- 5. You can answer questions in any order.

## Special Requirements: NONE

THIS EXAMINATION PAPER SHOULD NOT BE OPENED UNTIL PERMISSION HAS BEEN GIVEN BY THE INVIGILATOR.

# Question 1 [20 Marks]

- (a) Give clear definitions of the following terms:
  - (i) A convex set.
  - (ii) A convex function.
  - (iii) A concave function.
- (b) Let  $h: \mathbb{R}^n \to \mathbb{R}$  be a function of many variables and let  $k: \mathbb{R} \to \mathbb{R}$  be a function of one variable. Suppose h and k are both convex functions. Let  $x = (x_1, x_2, ..., x_n) \in \mathbb{R}^n$  and let  $y \in \mathbb{R}$ . Define a function  $f: \mathbb{R}^{n+1} \to \mathbb{R}$  as follows:

$$f(x,y) = h(x) + k(y).$$

Show that f is a convex function.

(c) For each function below, determine whether it is concave, convex or neither on the given set.

(i) 
$$f(x_1, x_2) = 2x_1^2 - 5x_1x_2 + 3x_2^2$$
 on  $\mathbb{R}^2$ .

(ii) 
$$f(x_1, x_2) = -x_1^2 - 2x_2^2$$
 on  $\mathbb{R}^2$ .

(iii) 
$$f(x_1, x_2) = -x_1 - 2x_2$$
 on  $\mathbb{R}^2$ . (3)

# Question 2 [20 Marks]

(a) Use the method of steepest descent to approximate the solution to the problem:

minimise 
$$f(x_1, x_2) = (x_1 - 2)^2 + x_1 + x_2^2$$
.

Begin at the point  $(\frac{5}{2}, \frac{3}{2})$ . (8)

(b) Find all local maxima, local minima, and saddle points of

$$f(x_1, x_2) = 3x_1^2x_2 + x_2^3 - 3x_1^2 - 3x_2^2 + 2.$$

(12)

(5)

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## Question 3 [20 Marks]

(a) Use Lagrange multipliers to solve the following problem.

minimise 
$$f(x_1, x_2, x_3) = x_1^2 + x_2^2 + x_3^2$$
  
subject to:  $x_1 + x_2 + x_3 = 1$ .

(10)

(5)

(b) Use K-T conditions to solve the following problem.

minimise 
$$f(x_1, x_2) = (x_1 - 4)^2 + (x_2 - 4)^2$$
  
subject to:  $x_1 + x_2 \le 4$   
 $x_1 + 3x_2 \le 9$ . (10)

## Question 4 [20 Marks]

(a) Write down the dual of the following linear programming problem without first converting it to a normal maximisation problem.

maximise 
$$z=x_1-2x_2$$
  
subject to:  $x_1+x_2\leq 4$ ,  
 $x_1-x_2=4$ ,  
 $x_1\geq 0$ ,  $x_2$  urs.

(b) Consider the following linear programming problem:

maximise 
$$z = 3x_1 + 6x_2 + 2x_3$$
  
subject to:  $3x_1 + 4x_2 + 2x_3 \le 200$ ,  
 $x_1 + 3x_2 + 2x_3 \le 100$ ,  
 $x_1, x_2, x_3 \ge 0$ .

Find the dual and solve the dual graphically. Use complementary slackness to find the optimal solution to the primal. (15)

## Question 5 [20 Marks]

(a) Consider the following linear programming problem:

maximise 
$$z=2x_1-x_2+x_3$$
  
subject to:  $3x_1+x_2+x_3\leq 50,$   
 $x_1-x_2+2x_3\leq 10,$   
 $x_1+x_2-x_3\leq 20,$   
 $x_1,x_2,x_3\geq 0.$ 

When the above problem is solved using the simplex method, it is found that in the optimal tableau,  $x_{BV} = (x_2, x_1, s_3)^T$ . Use the formulas to construct the optimal tableau of the LP. (8)

Hint: 
$$\begin{pmatrix} 1 & 3 & 0 \\ -1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1/4 & -3/4 & 0 \\ 1/4 & 1/4 & 0 \\ -1/2 & 1/2 & 1 \end{pmatrix}$$
.

(b) Consider the following linear programming problem with its optimal tableau.

maximise 
$$z = 3x_1 + 2x_2$$
  $z x_1 x_2 s_1 s_2 s_3$  rhs subject to:  $2x_1 + x_2 \le 100$ ,  $x_1 + x_2 \le 80$ ,  $0 1 0 1 -1 0 20$   $x_1, x_2 \ge 0$ .

Answer the following questions.

- (i) Find the range of values of  $c_1$  (the objective function coefficient of  $x_1$ ) for which the current BV remains optimal. (4)
- (ii) Find the range of values of  $b_2$  (the right-hand side of the second constraint) for which the current BV remains optimal. (4)
- (iii) A third activity  $x_3$  is being considered. If  $c_3 = 3.5$  and  $a_3 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ , determine if it is worth introducing this activity. (4)

Some Formulas: 
$$\bar{c}_j = c_{BV} B^{-1} a_j - c_j$$
,  $\bar{b} = B^{-1} b$ ,  $\bar{a}_j = B^{-1} a_j$ ,  $\bar{z} = c_{BV} B^{-1} b$ ,

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### Question 6 [20 Marks]

Consider the optimal control problem with state equation and cost function

$$\dot{x}_1 = x_1 + u_1, \quad J = \int_0^{t_1} \frac{1}{2} u_1^2 dt.$$

The initial and terminal states are  $x_1(0) = X$  and  $x_1(t_1) = 0$ , respectively.

Use the Pontryagin Maximum Principle to find the optimal control, the optimal trajectory, and the optimal cost.

### Question 7 [20 Marks]

Consider the controllable problem with state equations

$$\dot{x}_1 = x_2 + u_1, \quad \dot{x}_2 = 0, \quad |u_1| \le 1.$$

- (a) Find  $C(t_1,0)$ , the set of all points controllable to the origin in time  $t_1$ . (6)
- (b) Find C(0), the set of all points controllable to the origin. (2)
- (c) Find  $\mathcal{R}(t_1, x^0)$ , the set of reachable points from  $x^0 = (p, q)^T$  in time  $t_1$ .
- (d) Write down the state equations for the time-reversed problem and verify that  $\mathcal{R}(t_1,0)$  for the time-reversed problem is the same as  $\mathcal{C}(t_1,0)$  for the original problem. (6)

END OF EXAMINATION\_\_\_\_\_