

**UNIVERSITY OF SWAZILAND**

**Faculty of Science  
Department of Computer Science**

**Supplementary Examination, July 2011**

Title of paper: **COMPUTER ORGANISATION I**

Course numbers: **CS241**

Time allowed: 3 hours

Instructions: Answer any 4 out of the 5 questions. Each question carries 25 marks.

**THIS EXAMINATION PAPER SHOULD NOT BE OPENED UNTIL PERMISSION HAS BEEN GRANTED BY THE INVIGILATOR**

**Question 1**

- a) Define the following terms:
  - i. Integrated circuit
  - ii. LSI
  - iii. Programmable Logic Array
  - iv. Comparator
  - v. Asymmetric clock [5]
- b) Draw a diagram showing a NAND gate constructed using 2 transistors. [4]
- c) Draw a circuit diagram of an 3-to-8 decoder. [8]
- d) Draw a circuit diagram of a 1-bit left/right shifter. It must input a 4-bit value. [8]

**Question 2**

- a) Suppose that the following byte values (shown in hexadecimal) are found in 4 consecutive memory locations starting at address 512:  
10 20 04 08
- i. What is the 2-byte value at address 514, assuming little-endian representation?
  - ii. What is the 4-byte value at address 512, assuming big-endian representation? [2]
- b) Discuss the 3 main factors that are seen to vary across the memory hierarchy. [6]
- c) Distinguish between each of the following pairs:
- i. Bus master and slave.
  - ii. Synchronous and asynchronous buses. [4]
- d)
- i. What is bus arbitration, and why it is needed? [2]
  - ii. With the aid of a diagram, describe how bus arbitration can be carried out by daisy chaining. [5]
- e) Define each of the following, and explain how each one can improve the performance of computers:
- i. Cache
  - ii. Multiprocessing [6]

**Question 3**

- a) State the full name and purpose of the following pins in memory chips: OE, RAS and CAS. [3]
- b) Give 2 reasons why DRAM is preferable to SRAM in cell phones. [2]
- c) List any 4 kinds of ROM chips, and describe the main characteristic of each. [8]
- d) An FPM-type memory chip has 4 pins for address input and 8 pins for data input/output.
- i. Draw the pin diagram of the chip including strobe lines. [3]
- ii. Work out the memory capacity of this chip. [2]
- e) Draw a diagram of a 2-bit register chip comprised of D flip-flops. It should have a total of 8 pins numbered as follows:
- pins 1 and 2 for data input
  - pin 3 for clock (writing to register is enabled at high-to-low transition)
  - pin 4 for ground
  - pins 5 and 6 for data output
  - pin 7 for clear (forces 00 data to be written into register)
  - pin 8 for power

Clearly show connections from pins to flip-flops (except power and ground). [7]

#### Question 4

- a) What is the main difference between the B and C buses of the Mic-1 CPU? [1]
- b)
- i. What roles do the two Mic-1 registers, MPC and MIR, play in controlling the execution of microprograms? [2]
  - ii. MIR is divided into 6 fields. What is the purpose of each field? [6]
  - iii. Draw the timing diagram of a single data path cycle in Mic-1. On the diagram, indicate the timing of the following events:
    - Updating MPC.
    - Updating MIR.
    - Propagating control signals. [3]
- c)
- i. Discuss the role played by the following Mic-1 registers in accessing main memory: MAR, MDR, PC and MBR. [4]
  - ii. Explain the reason for the following observation: 'When the Mic-1 initiates a memory read operation in cycle  $k$ , the result only becomes available for use in cycle  $k+2$ .' [2]
- d) What work is done by a microcode assembler? [1]
- e) The following Mic-1 microinstruction will lead to the propagation of several control signals. For each control signal, precisely state where it will be directed, and what effects it will cause upon arrival.  

$$\text{MDR} = \text{OPC} = \text{H} + \text{TOS}; \text{wr}$$
 [6]

**Question 5**

Write four Mic-1 microprograms to carry out the following tasks:

- a) Swap the OPC and CPP registers. [3]
- b) Compute  $-(H + TOS - MDR)$  and write the result to H. [4]
- c) Swap the contents of addresses 0 and 1 in main memory. [8]
- d) Check whether H register is zero. If so, write 1 to H, otherwise multiply H by 2. [10]

**\*\*\* END OF PAPER \*\*\***

---

**Mic-1 Data Sheet – List of ALU Functions**

$A, B, \bar{A}, \bar{B},$   
 $A+B, A+B+1, A+1, B+1,$   
 $B-A, B-1, -A,$   
 $A \text{ AND } B, A \text{ OR } B,$   
 $0, 1, -1$

(The ALU's left and right inputs are denoted  $A$  and  $B$ , respectively.)

---